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# SIMULTANEOUS PEOPLE TRACKING AND RECOGNITION WITH A SERVICE ROBOT



Condition: New. Publisher/Verlag: VDM Verlag Dr. Müller | A novel approach using sensor fusion and Bayesian estimation | The research proposed in this book investigates new methods for service robots to detect people using sensor data fusion, and to estimate their position and identity simultaneously. An efficient multisensor solution for human detection is presented, where a mobile robot uses its on-board camera and laser to search for faces and legs in the environment. A new tracking algorithm based on the...

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- Authored by Bellotto, Nicola
- Released at -



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